

VECTORS

The concept of vectors is of particular importance to physicists. A vector is a quantity that has both magnitude and direction. This is as opposed to scalar quantities which have only a magnitude.

e.g.:

Vectors

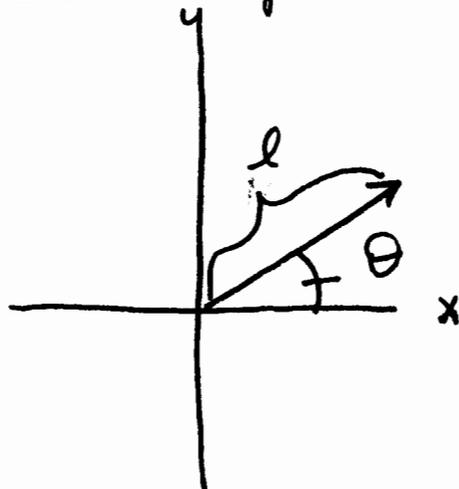
- velocity = 60 mph south
 - displacement = distance moved (it makes a difference if a punter kicks a football 100 yds str up or 100 yds down field)
 - force (may it be with you - in your direction - rather than against you)
- We will encounter a large no. of vector quantities in this course and it will be imp. to know how to treat them.

Scalars

- Speed = 60 mph (the car doesn't care which direction)
- Temperature ($^{\circ}$)
- Time (h m s)
- Relative Humidity (90)
- Interest rate
- energy

We denote vectors by **BOLD FACE** type (as the text does) or by an arrow (as we'll do in.

In two dimensions we require two numbers to specify a vector. Intuitively these are a magnitude and a direction
 = components (length = l) (angle = θ)



Walk 45 paces
 NE to the treasure

$$l = 45 \text{ paces} \approx 45 \text{ m}$$

$$\theta = 45^\circ$$

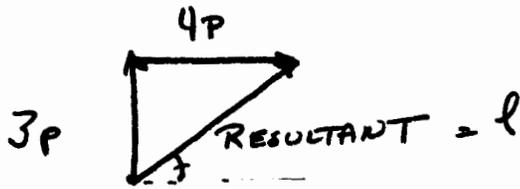
(We note parenthetically that only for displacement [distance] is this graphical representation absolutely true, everything else is a scaled representation (e.g. 1 cm on the paper represents 10 km s^{-1} , etc))

Given a ruler and a protractor one may add vectors graphically:

Long John Silver walks 3 paces north

↑ then 4 paces east →

to find the final displacement (resultant) of Long John Silver



If we measure we will find
 $l = 5 \text{ paces}$ $\theta = 37^\circ$

We can take any arbitrary no of vectors
 (e.g. 4 paces NNW, 3 paces N, 2 paces ENE)
 and add them together graphically by
 placing the "foot" of our vector at the
 "head" of the previous vector to find the
 resultant or "head tail
 distance"

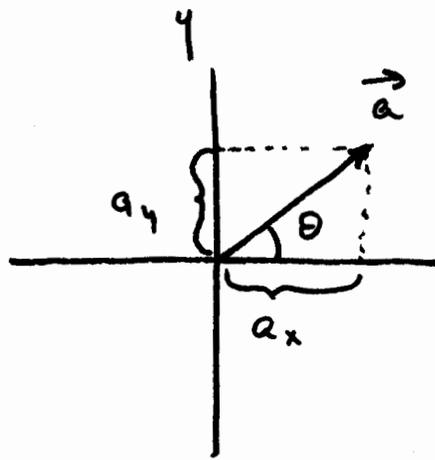


But this is a cumbersome process.

We may, however, specify vectors by
 different components in Cartesian
 Coordinate System:

$$\text{Instead of } \vec{a} = (l, \theta)$$

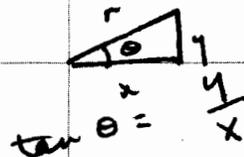
$$\text{we use } \vec{a} = (a_x, a_y)$$



Trig def'ns:

$$\sin \theta = \frac{y}{r}$$

$$\cos \theta = \frac{x}{r}$$



$$a_x = |a| \cos \theta$$

$$a_y = |a| \sin \theta$$

In the above, simple example we have

$$\vec{a}_1 = (0, 3 \text{ paces})$$

$$\vec{a}_2 = (4 \text{ paces}, 0)$$

To add these vectors we simply add the components separately

$$a_x = a_{1x} + a_{2x} \quad (= 0 + 4)$$

$$a_y = a_{1y} + a_{2y} \quad (= 3 + 0)$$

Thus $\vec{a} = (4 \text{ paces}, 3 \text{ paces})$

In general

$$a_x = \sum_i a_{ix}$$

$$a_y = \sum_i a_{iy}$$

for any number of vectors

Recalling our geometry

This denotes the magnitude

$$|\vec{a}|^2 = a_x^2 + a_y^2 = 4^2 + 3^2 = 25$$

$$|\vec{a}| = 5 \text{ paces}$$

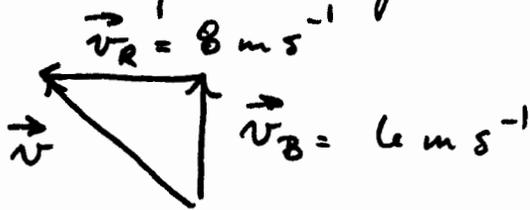
Relating to the angle

$$\tan \theta = \frac{a_y}{a_x} = 0.75$$

$$\theta = \tan^{-1} 0.75 = 37^\circ$$

For most applications in this course we'll find the cartesian notation most useful. Now that we have the basics let's try a few games:

- (1) A boat which can travel 6 m s^{-1} heads north across a rapid section of the Colorado which is traveling west at 8 m s^{-1} ; what is the resultant velocity (magnitude + direction)



$$|v|^2 = 6^2 + 8^2 = 36 + 64 = 100$$

$$|v| = 10 \text{ m s}^{-1}$$

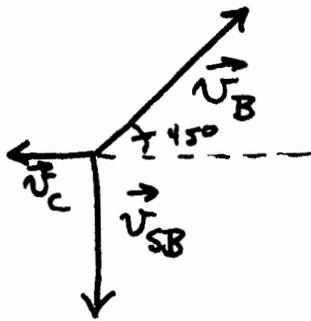
$$\vec{v} = \vec{v}_B + \vec{v}_R$$

$$= (0, 6 \text{ m s}^{-1}) + (-8 \text{ m s}^{-1}, 0)$$

$$\vec{v} = (v_x, v_y) = (-8 \text{ m s}^{-1}, 6 \text{ m s}^{-1})$$

But armed with these tools we can tackle more difficult problems:

Consider a boat headed NE at 10 m s^{-1} with a current of 2 m s^{-1} W. On the boat is a skateboarder who is moving 4 m s^{-1} S (wrt the boat). What is his velocity relative to the shore we have then



$$\begin{aligned}\vec{v}_B &= (10 \text{ m s}^{-1} \cos 45^\circ, 10 \text{ m s}^{-1} \sin 45^\circ) \\ &= (7.07 \text{ m s}^{-1}, 7.07 \text{ m s}^{-1})\end{aligned}$$

$$\vec{v}_C = (-2 \text{ m s}^{-1}, 0 \text{ m s}^{-1})$$

$$\vec{v}_{SB} = (0 \text{ m s}^{-1}, -4 \text{ m s}^{-1})$$

$$\begin{aligned}v_x &= 7.07 \text{ m s}^{-1} + (-2 \text{ m s}^{-1}) + 0 \text{ m s}^{-1} \\ &= 5.07 \text{ m s}^{-1}\end{aligned}$$

$$\begin{aligned}v_y &= 7.07 \text{ m s}^{-1} + 0 \text{ m s}^{-1} + (-4 \text{ m s}^{-1}) \\ &= 3.07 \text{ m s}^{-1}\end{aligned}$$

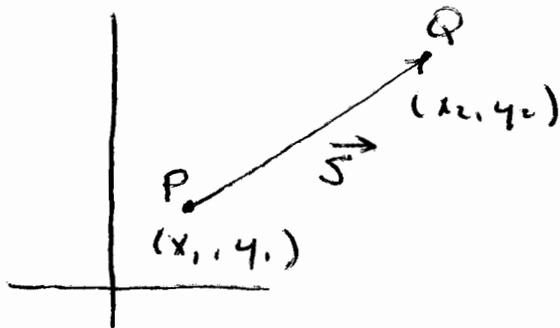
$$\vec{v} = (5.07 \text{ m s}^{-1}, 3.07 \text{ m s}^{-1})$$

$$|\vec{v}| = 6 \text{ m s}^{-1} \quad \theta = \tan^{-1} \frac{v_y}{v_x} = 31^\circ$$

MOTION IN A PLANE

Today we are going to begin to expand our treatment of motion from the one dimensional case to two dimensions. Much of what we discuss will be strangely familiar - we've covered most of it before in talking about rectilinear motion. Basically we have the same quantities: displacement, velocity, acceleration, force. In 2d motion we must deal with the vector nature of these quantities.

Displacement \vec{s}



$$|\vec{s}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

$\vec{s} = \vec{s}(t)$ Because \vec{s} is a vector, may treat components separately $x = x(t)$ $y = y(t)$